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**AUTOMOTIVE
CONFERENCE 2023**
Europe

SDV: Integrating Simulink C++ Code in Android Automotive Environment

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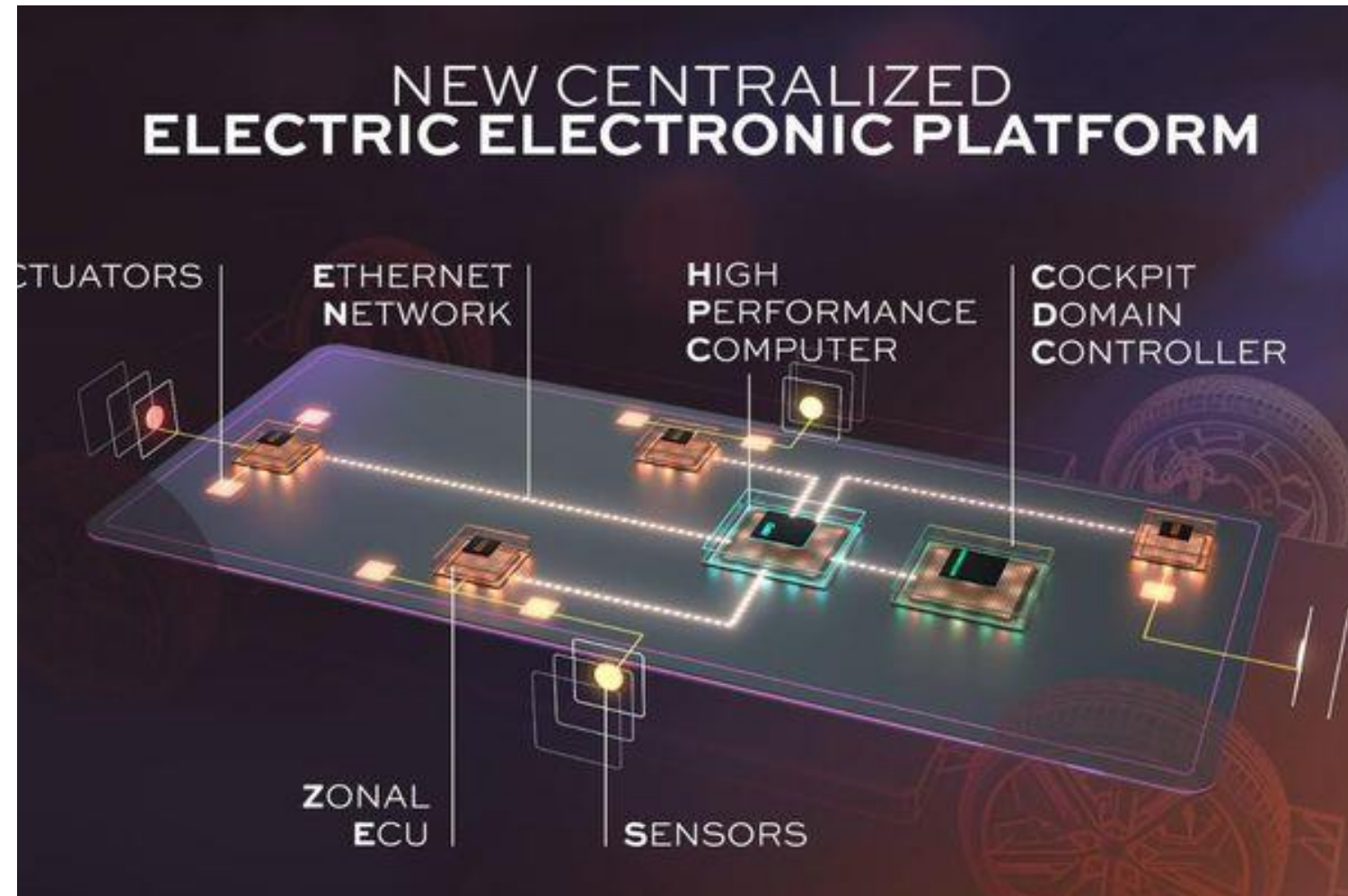


Agenda

- “Software Defined Vehicle” context: HPC, SOA, Top-Down development
- Proof of Concept: Connecting Models to Android Inter-Process Communication
- Demo: Climate Control example running on an Android Virtual Machine
- Conclusion and next steps

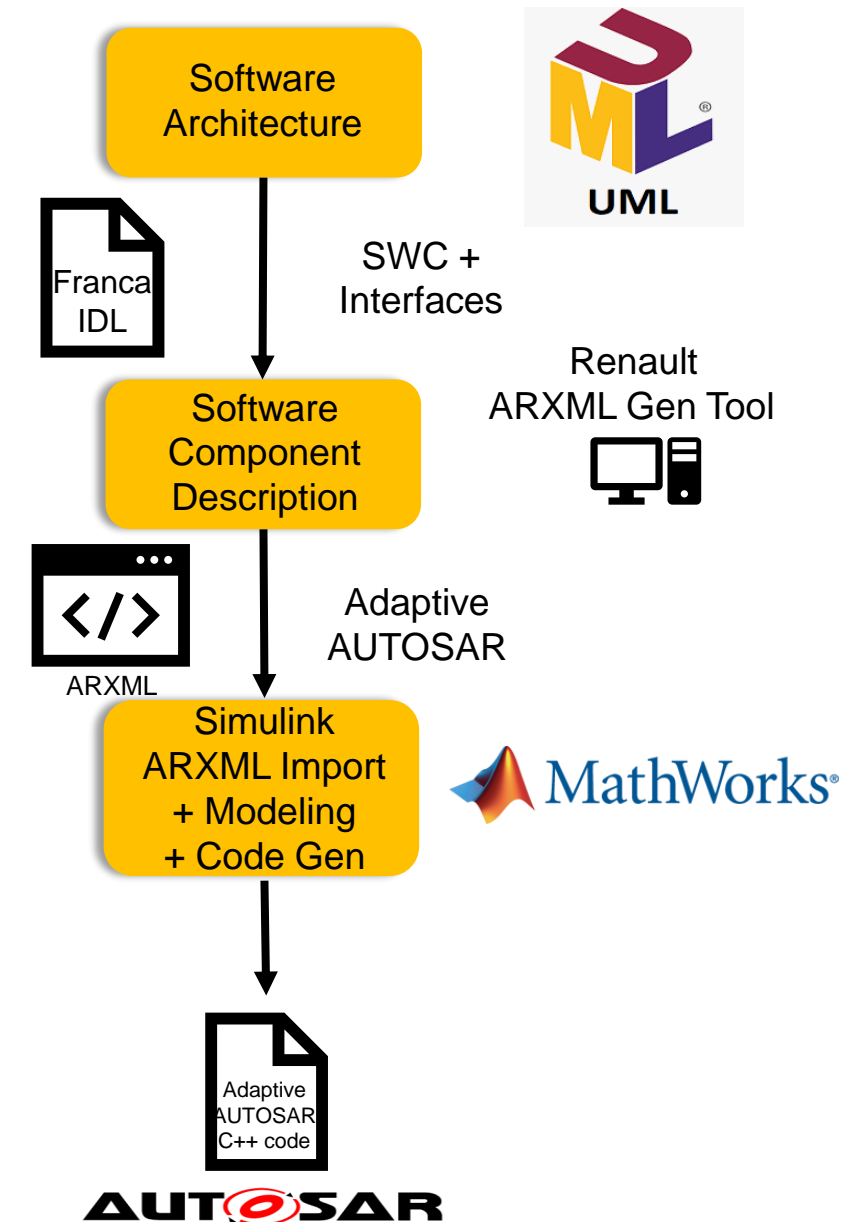
Context: Renault overall vision for Electric Electronic Platform

- Centralized EE Architecture
- Service Oriented Architecture (System + SW)
- Scalable and Upgradable Platform



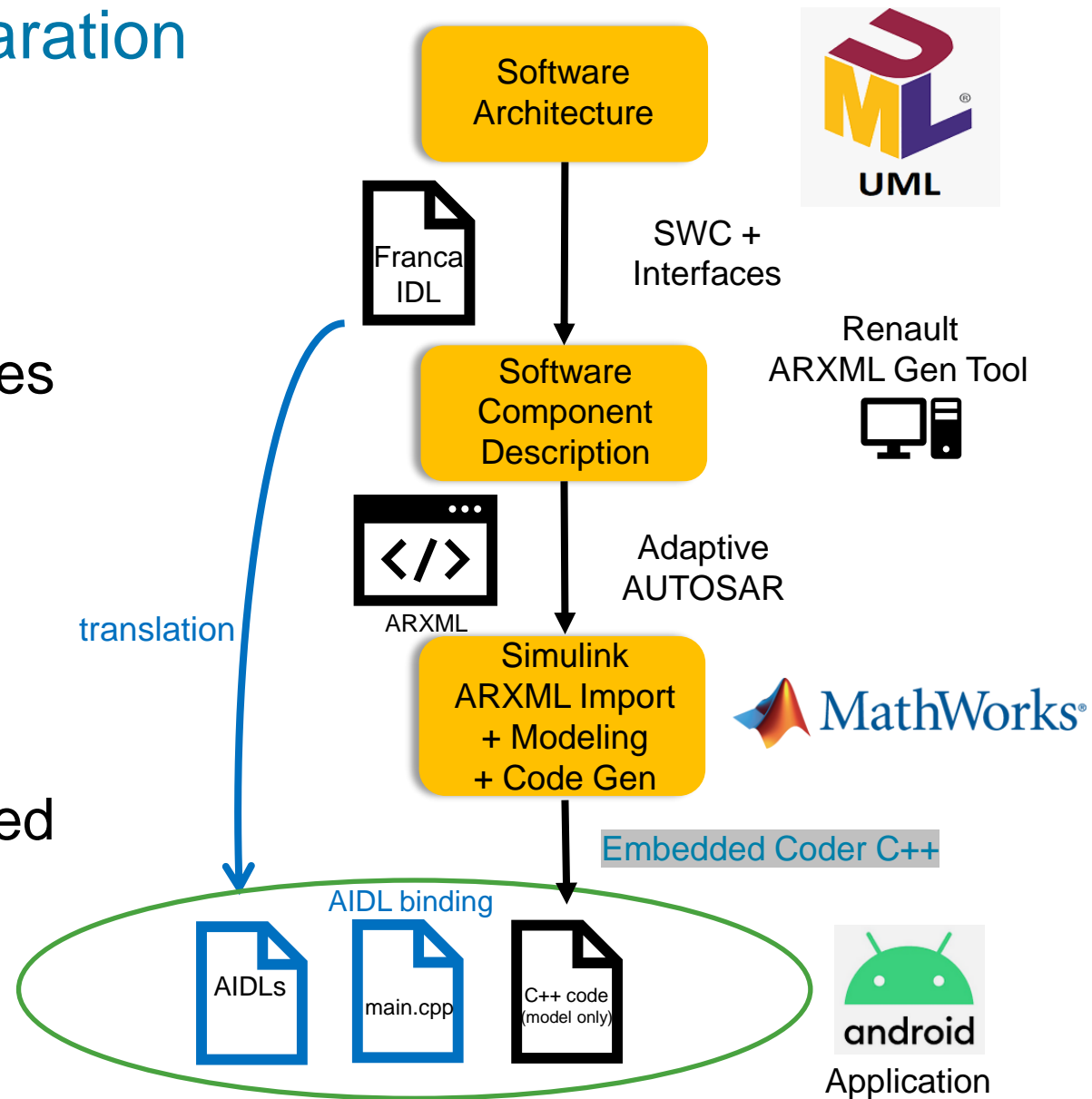
Context: Renault upstream project “FACE” (Future Architecture for Automotive Computing Environment)

- Top-Down development flow from Software Architecture to Implementation (Body, ADAS, and Chassis domains)
- Adaptive AUTOSAR running on High Performance Computer
- Service Oriented Architecture (Request/Response methods, events)



Context: Renault SDV Project preparation

- Renault strategic collaboration with Google: Android Automotive OS replaces Adaptive AUTOSAR
- New Interface Definition Language: Android IDL (used for IPC generation)
- Service Oriented Architecture maintained (Request/Response methods => RPC, events => RPC + Callbacks)



RPC: Remote Procedure Call
IPC: Inter-Process Communication

Introduction to Android AIDL binders with a simple example

- Inter-Process Communication / Remote Procedure Call using AIDL Binder :
- MATLAB Simulink modeling
- Embedded Coder C++ code generation: UML Class Diagram representation
- AIDL definition and C++ Binder generation
- C++ Glue code (application main program)

Introduction to Android AIDL binders with a simple example

The Client side diagram shows a 'step' block connected to a 'swcClient_triggered_sys' block. Inside this block, a 'ServiceExample' block contains a 'doSomething()' call. A 'Function Caller' label points to the 'doSomething()' call, and a 'Function Element' label points to the 'ServiceExample' block. A signal 'ServiceExample.doSomething' is shown at the bottom.

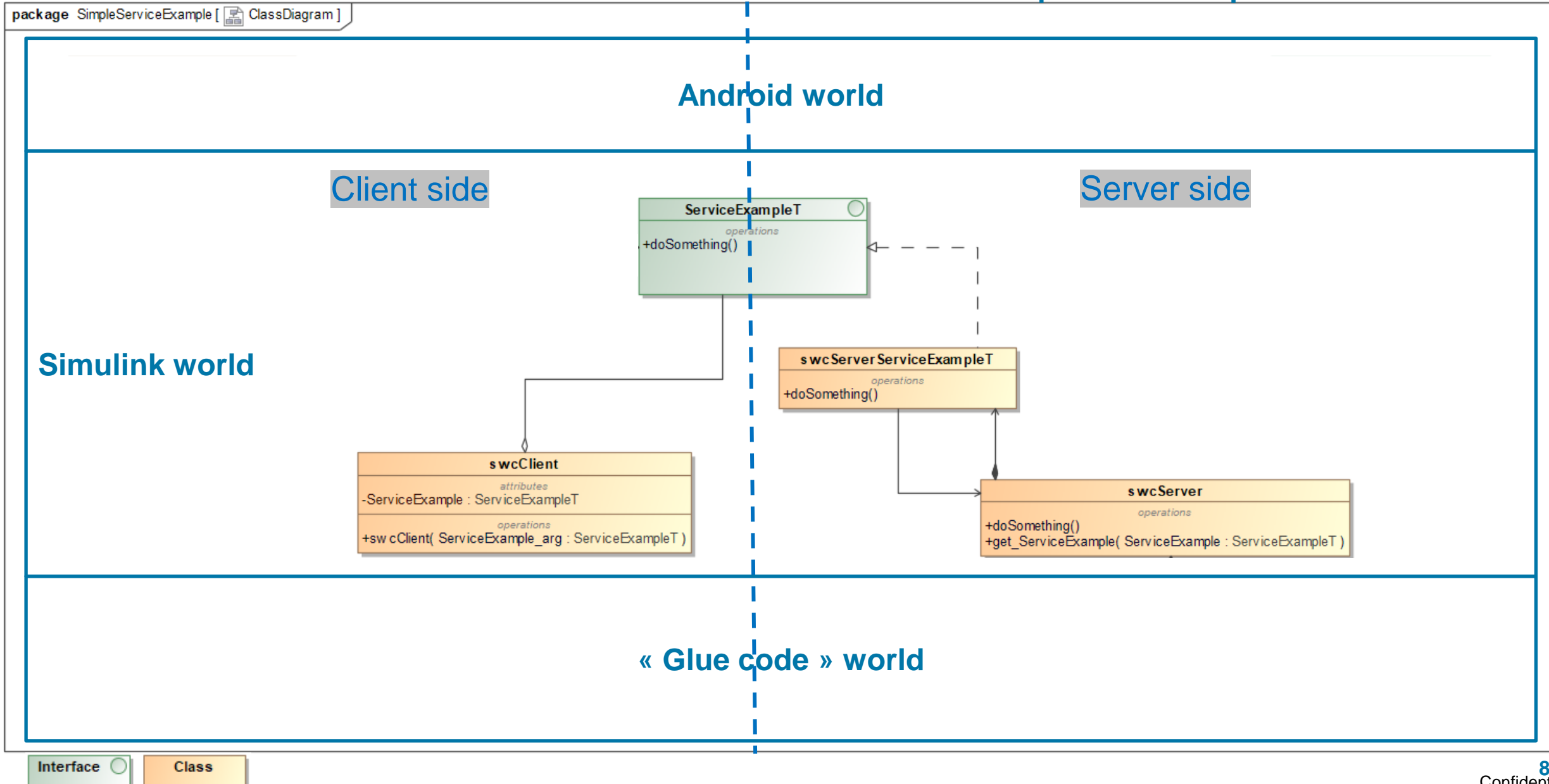
Source	#	Signal Name	Data Type	Min	Max	Dimensions	Complexity	Sample Time	Unit	Resolve
step	1		Inherit: auto			-1	auto	0.025	inherit	
ServiceExample.doSomething	2		Inherit: auto			-1	auto	-1	inherit	

The Server side diagram shows a 'ServiceExample.doSomething_Server' block connected to a 'doSomething()' block. The 'doSomething()' block is labeled 'function' and 'sys_ServiceExample_doSomething'. A 'Simulink Function' label points to the 'doSomething()' block. A signal 'ServiceExample.doSomething' is shown at the top.

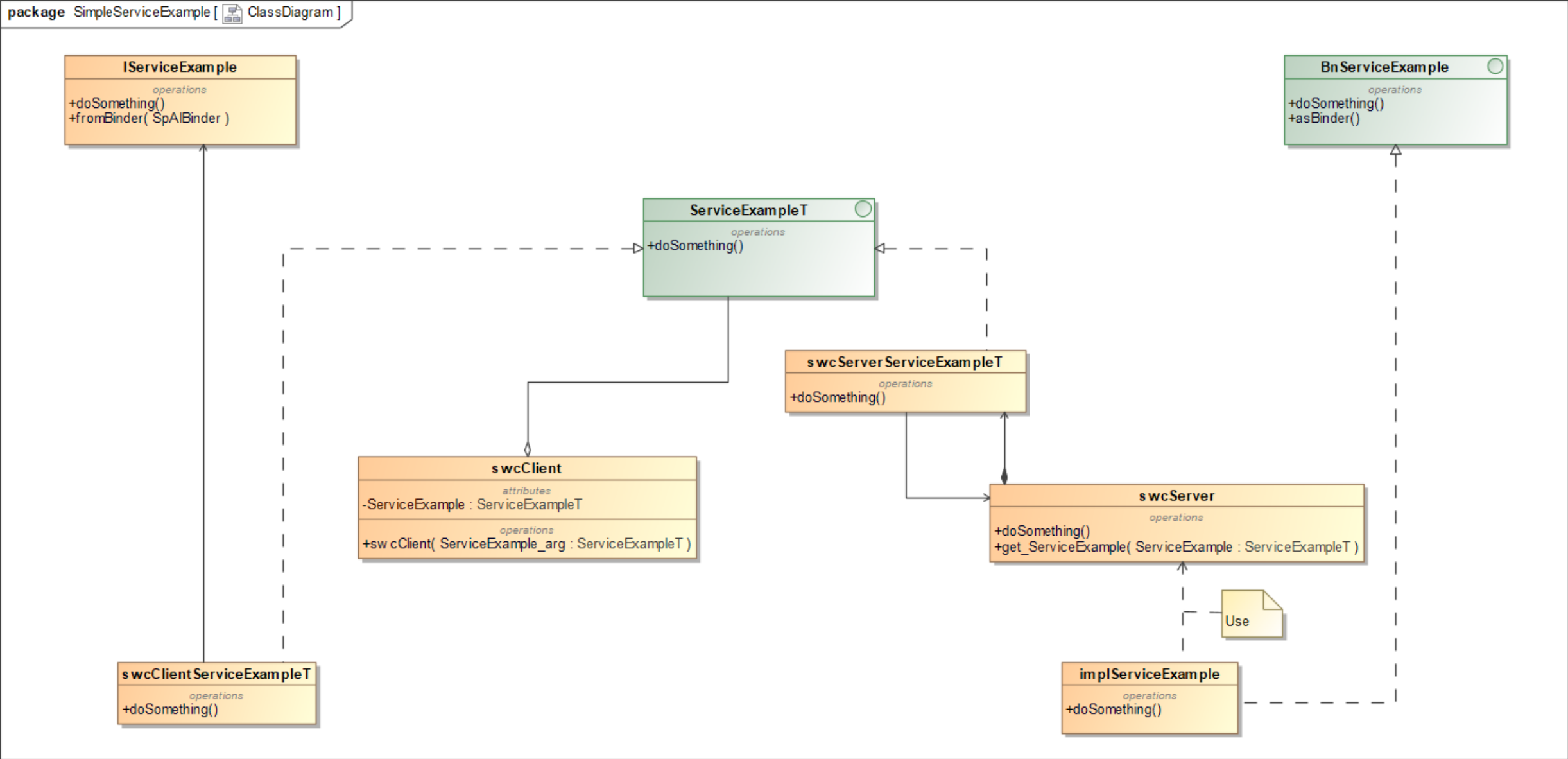
Source	#	Signal Name	Data Type	Min	Max	Dimensions	Complexity	Sample Time	Unit	Resolve
ServiceExample.doSomething	1		Inherit: auto			-1	auto	-1	inherit	

A simple interface example with one method (no argument)

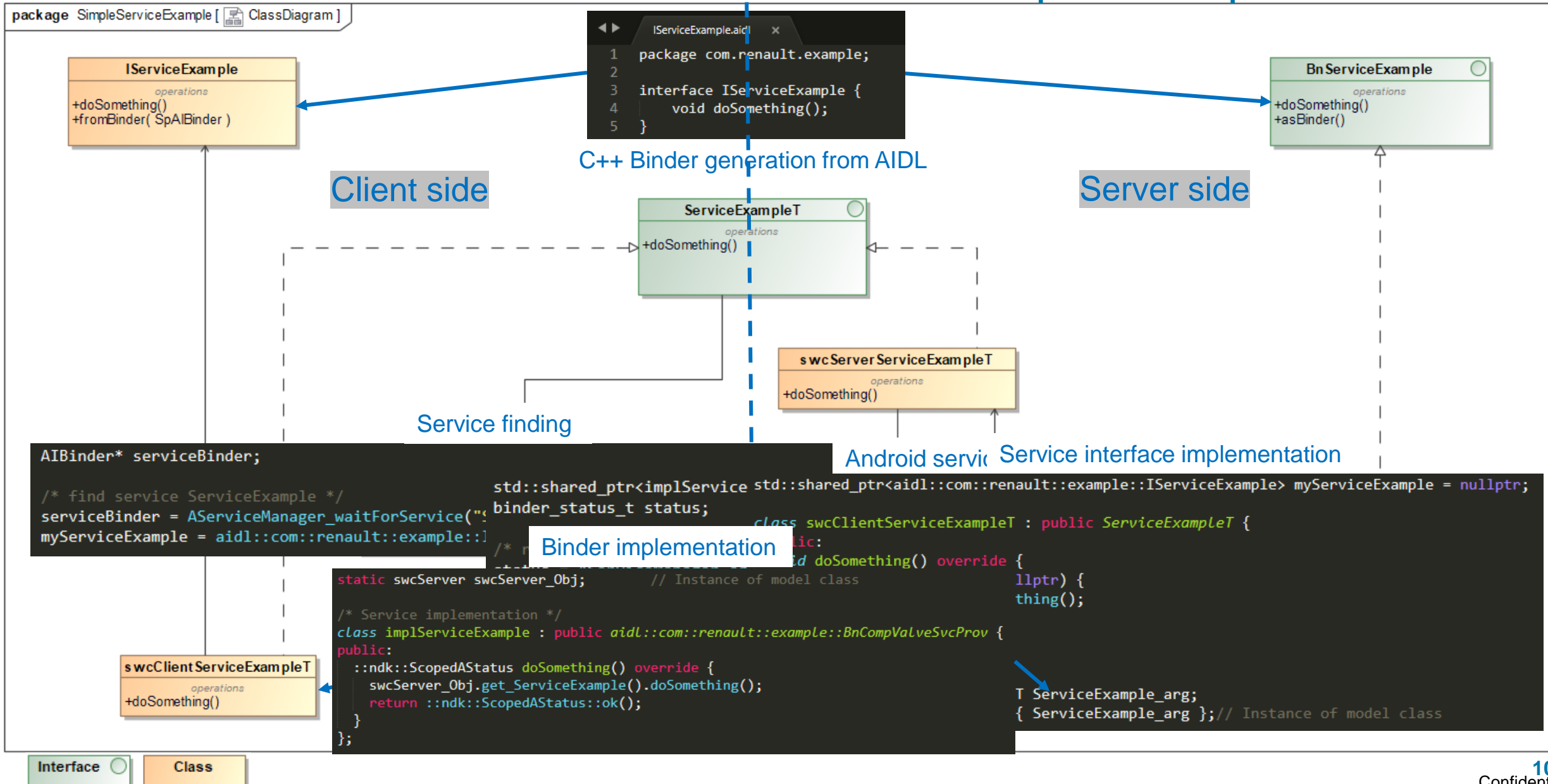
Introduction to Android AIDL binders with a simple example



Introduction to Android AIDL binders with a simple example



Introduction to Android AIDL binders with a simple example



Climate Control Proof Of Concept

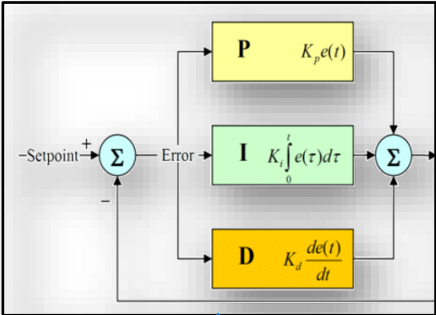
- A control loop (25ms) driving a compressor (cold air)
- A compressor and an evaporator as plant model
- An HMI to activate the climate control and to select the temperature setpoint
- A Service Oriented Architecture using a Request/Response method and Events
- Console output every 250ms for the demo

Climate Control PoC

HMI

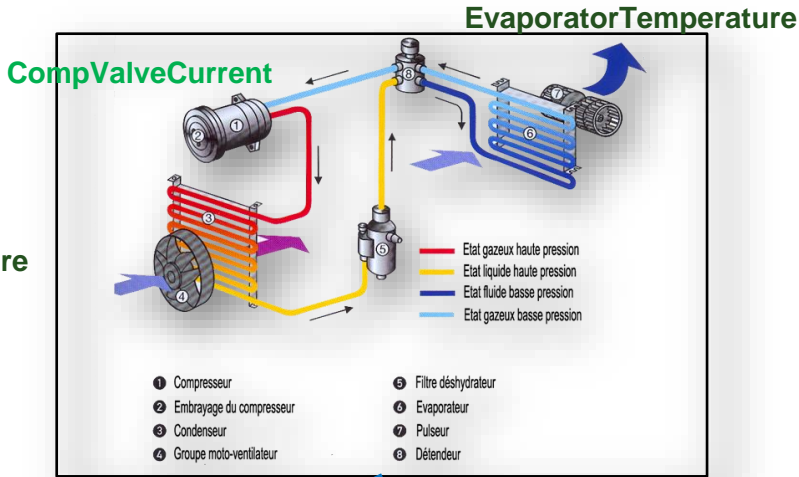


ColdSourceTempNeed



CompValveCurrent

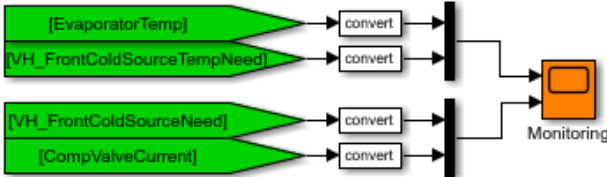
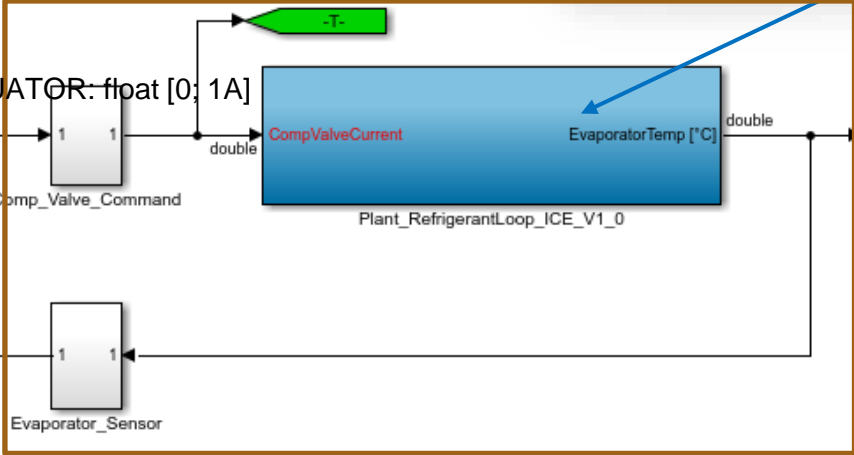
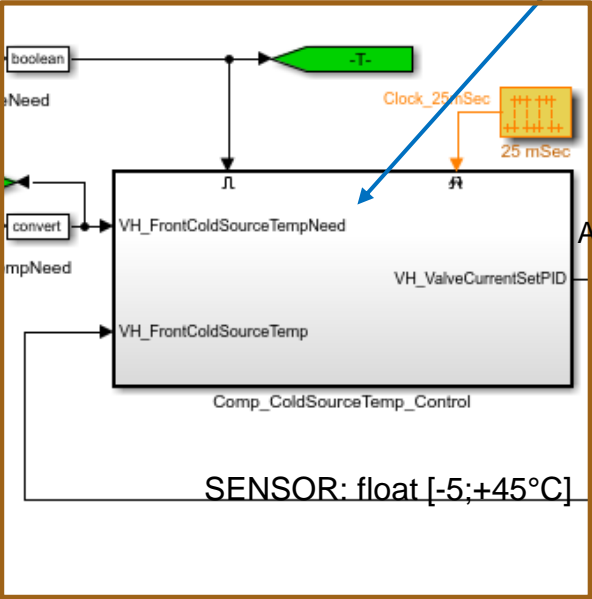
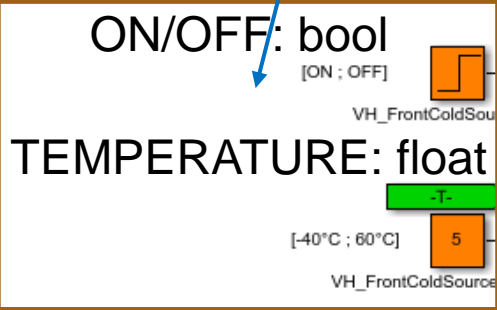
EvaporatorTemperature



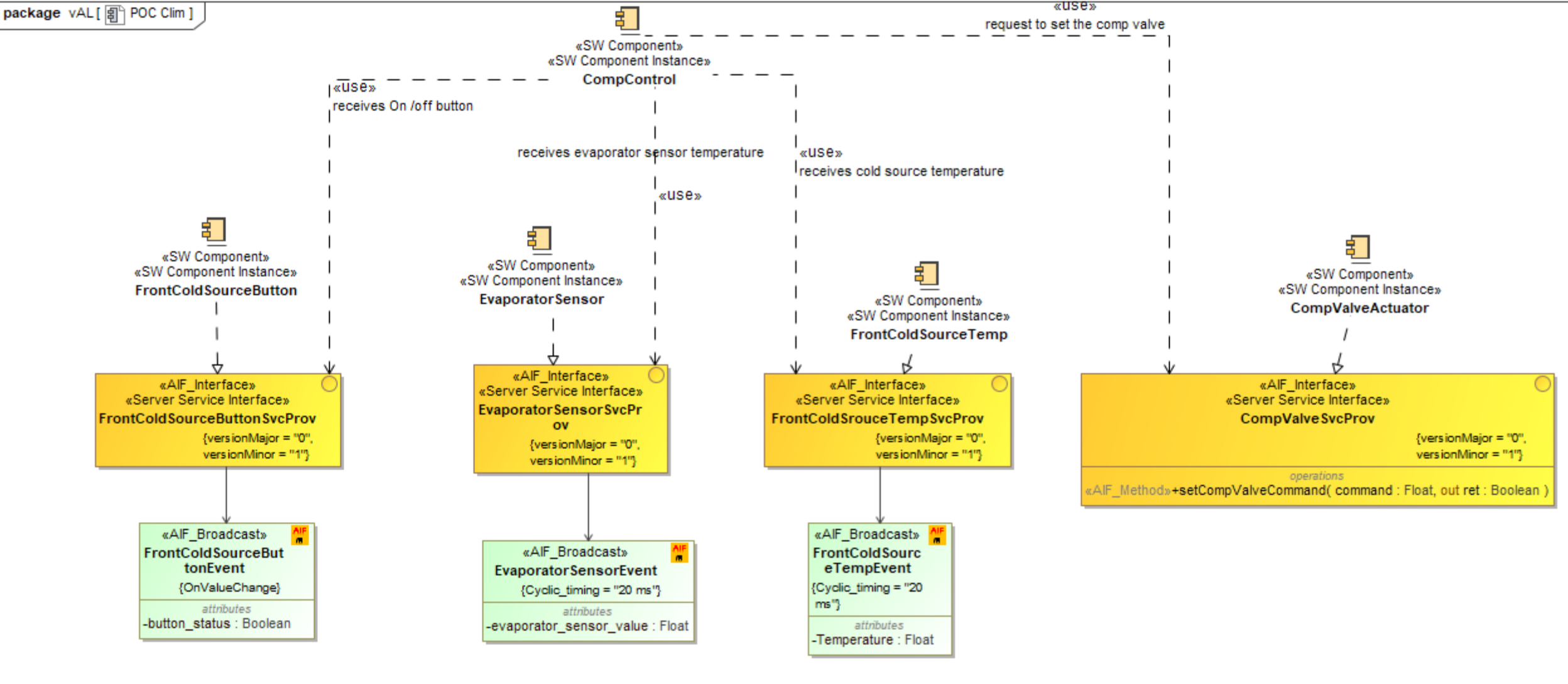
swcCompCommand model

swcCompControl model

swcRefrigerantLoop model



Climate Control PoC Software Architecture (UML Diagram)



Climate Control PoC Software Architecture (UML Diagram)

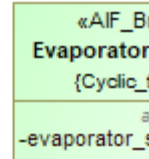
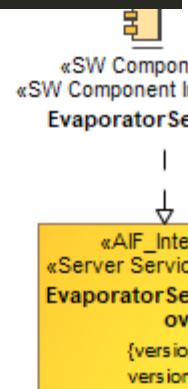
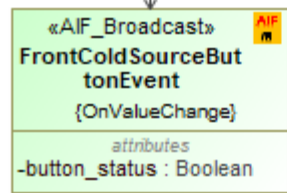
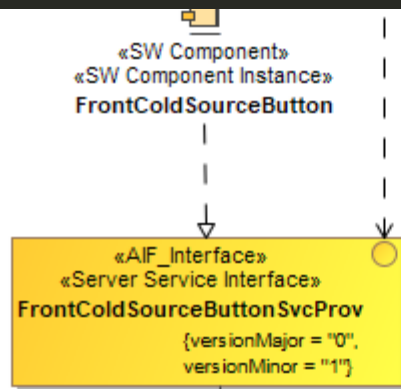
FIDL extraction

AIDL translation

```

1 package com.renault.climbox;
2
3 interface ICompValveSvcProv {
4     boolean setCompValveCommand(float command);
5 }

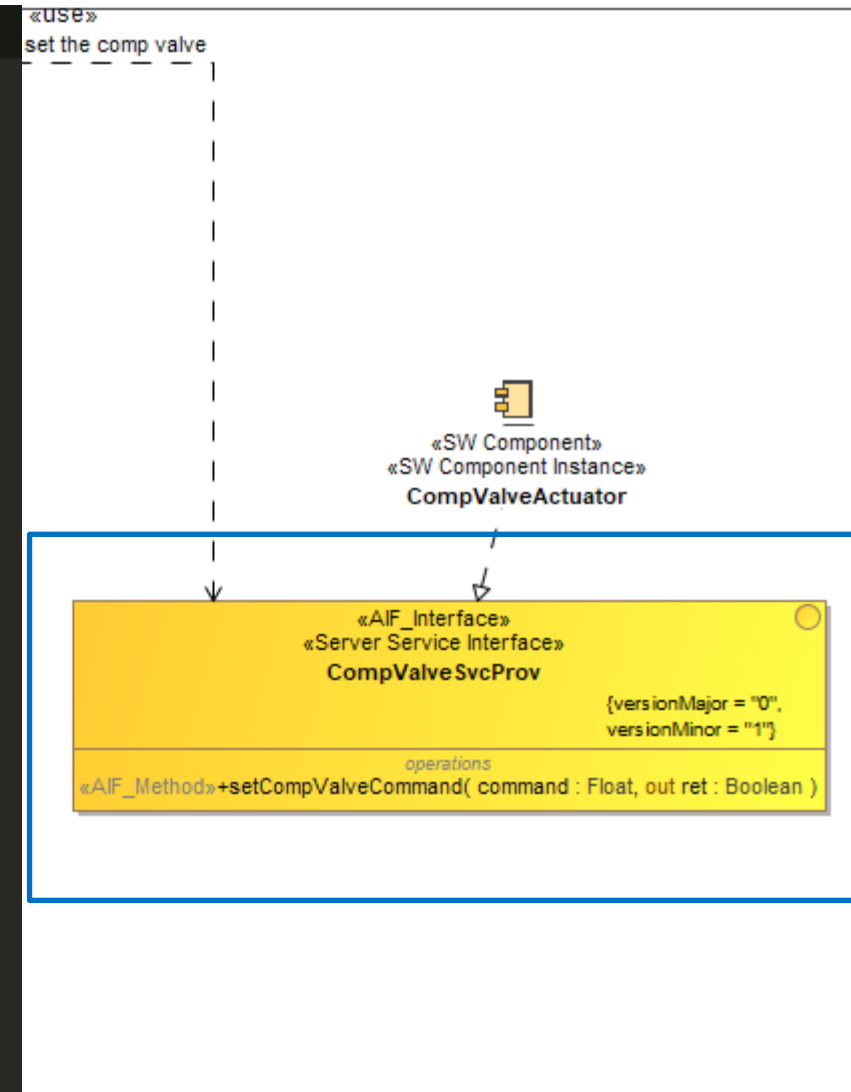
```



```

1 package CompValveSvcProv
2
3
4 <<*>
5     @description :
6
7 <<*>
8
9 interface CompValveSvcProv {
10     version { major 0 minor 1 }
11
12
13 <<*>
14     @description :
15
16
17     @experimental: asil-level : ASIL_QM
18 <<*>
19     method setCompValveCommand {
20         in
21         {
22             <<*>
23                 @description :
24
25             <<*>
26                 Float command
27         }
28         out
29         {
30             <<*>
31                 @description :
32
33             <<*>
34                 Boolean ret
35         }
36     }
37 }

```



Climate Control PoC Simulink models

The screenshot displays the Simulink environment for a climate control PoC model. The interface includes a top menu bar with tabs for SIMULATION, DEBUG, MODELING, FORMAT, and APPS. Below the menu is a toolbar with various modeling tools such as Model Advisor, Compare, Model Data Editor, Model Explorer, Schedule Editor, Model Settings, Insert Subsystem, Atomic Subsystem, Variant Subsystem, Subsystem Reference, Referenced Model, Insert Chart, and Insert Area. The main workspace shows a hierarchical model structure in the Model Browser on the left, with the following components:

- POC_Sweet500
 - swcCompCommand (swcCompCommand)
 - swcCompControl (swcCompControl)
 - swcCompControl_triggered_sys
 - Enabled Subsystem
 - dPL_Corrector
 - swcRefrigerantLoop (swcRefrigerantLoop)
 - svcCompValveSvcProv_setCompValveCommand_sys
 - swcRefrigerantLoop_triggered_sys
 - Enabled Subsystem
 - Plant_RefrigerantLoop_ICE_V1_0

The main workspace contains three interconnected subsystem blocks:

- swcRefrigerantLoop**: Contains a 'step' input and a 'svcEvaporatorSensorSvcProv_evaporator_sensor_value' output.
- swcCompControl**: Contains a 'step' input, a 'svcCompValveSvcProv' output, and a 'svcEvaporatorSensorSvcProv_evaporator_sensor_value' output.
- swcCompCommand**: Contains a 'svcFrontColdSourceButtonSvcProv_button_status' output (boolean) and a 'svcFrontColdSourceTempSvcProv_Temperature' output (single).

Connections between the subsystems include:

- The 'step' input of swcRefrigerantLoop is connected to the 'step' input of swcCompControl.
- The 'svcCompValveSvcProv' output of swcRefrigerantLoop is connected to the 'svcCompValveSvcProv' input of swcCompControl.
- The 'svcEvaporatorSensorSvcProv_evaporator_sensor_value' output of swcRefrigerantLoop is connected to the 'svcEvaporatorSensorSvcProv_evaporator_sensor_value' input of swcCompControl.
- The 'svcFrontColdSourceButtonSvcProv_button_status' output of swcCompCommand is connected to the 'svcFrontColdSourceButtonSvcProv_button_status' input of swcCompControl.
- The 'svcFrontColdSourceTempSvcProv_Temperature' output of swcCompCommand is connected to the 'svcFrontColdSourceTempSvcProv_Temperature' input of swcCompControl.

At the bottom of the window, the status bar shows 'Ready', 'View 3 warnings', '139%', and 'FixedStepDiscrete'. A 'Confidential' watermark is visible in the bottom right corner.

Climate Control PoC Simulink models

The image shows the Simulink environment for a Climate Control PoC model. A 'Target selection' dialog box is open, showing the following configuration:

- System target file: ert.tlc
- Description: Embedded Coder
- Language: C++
- Language standard: C++11 (ISO)

The Simulink model diagram consists of three main blocks:

- swcRefrigerantLoop**: Contains a 'step' input and a 'svcEvaporatorSensorSvcProv_evaporator_sensor_value' output.
- swcCompCommand**: Contains a 'svcFrontColdSourceButtonSvcProv_button_status' output and a 'svcFrontColdSourceTempSvcProv_Temperature' output.
- swcCompControl**: Contains a 'step' input, a 'svcCompValveSvcProv' output, and a 'svcFrontColdSourceTempSvcProv_Temperature' output.

Connections between blocks are as follows:

- swcRefrigerantLoop (step) to swcCompControl (step)
- swcRefrigerantLoop (single) to swcCompControl (single)
- swcCompCommand (boolean) to swcCompControl (boolean)
- swcCompCommand (single) to swcCompControl (single)

Blue annotations highlight the following interfaces:

- Event interface**: Points to the 'step' signal connection.
- Method interface**: Points to the 'single' signal connection.
- Message Client/Server**: Points to the 'boolean' and 'single' signal connections.

Referenced Files:

- swcCompCommand.slx
- swcCompControl.slx
- swcRefrigerantLoop.slx

Demo!

- Running on Google Cloud Workstation
- Launching Android Cuttlefish VM (Android Open-Source Platform: AOSP)
- Launching Android debug environment (adb)
- Launching 3 applications (Software Components), communicating together:
 - swcCompCommand
 - swcCompControl
 - swcRefrigerantLoop

The screenshot displays a Cloud Workstation environment. At the top, a browser window shows the URL `80-workstation-remy.cluster-ka5fx5e64vbzuxtptgptlgzjo4.cloudworkstations.dev/?authuser=0`. Below the browser, the main workspace is divided into two terminal panes. The left pane is titled `Android_VM` and the right pane is titled `adb`. Both panes show a shell prompt `user@workstation-remy:~/caros$`. At the bottom of the interface, there is a `TERMINAL` section with three additional terminal panes, each also showing the `user@workstation-remy:~/caros$` prompt. On the right side of the terminal section, a file explorer is open, displaying a tree view with the following items: `swcCompCommand`, `CompControl`, `RefrigerantLoop`, and `bash`. The bottom status bar shows system icons on the left and the text `Layout: French` on the right.

Conclusion

- MATLAB Simulink is able to model SWC in Service-Oriented Architecture
- Embedded Coder C++ code generation is easy to connect to an object-oriented RPC inter-process communication like Android offers with AIDL Binders
- Next technical steps to complete the demonstration:
 - Write a MATLAB script to import AIDLs interfaces in System Composer to create SWC model
 - Automate main program (glue code) generation from AIDLs

Thank you for your attention!

Any Questions?